## **Theory of Stellar Oscillations**

#### Margarida S. Cunha



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Azores, 17-27 July, 2016

#### COURSE 7

#### LINEAR ADIABATIC STELLAR PULSATION

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#### ASTRONOMY AND ASTROPHYSICS LIBRARY

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## Asteroseismology

J.-P. Zahn and J. Zinn-Justin, eds. Les Houches, Session XLVII, 1987 Dynamique des fluides astrophysiques Astrophysical fluid dynamics © 1993 Elsevier Science Publishers B.V. All rights reserved



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## **Brief introduction**

How would you describe a wave?



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Wave: propagation of information (a perturbation) in space and time

Wave in a supporting medium: material does not need to move from one point of the space to the other to propagate the information





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Wave in a supporting medium: material does not need to move from one point of the space to the other to propagate the information





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Waves propagate within stars



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Wave properties (e.g. frequencies) depend on properties of the medium where they propagate (density, pressure, etc.)



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$$\downarrow$$
Properties =  $f$  (interior)



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Waves propagate within stars

Wave properties (e.g. frequencies) depend on properties of the medium where they propagate (density, pressure, etc.)

$$\mathbf{Properties} = f \text{ (interior)}$$



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One mode  $\Leftrightarrow$  one piece of information

Average information on propagation cavity

With several modes one can hope to get localized information



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## Asteroseismology: Across the HR diagram

Kurtz 2010 adapted from Aerts et al. 2010





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## Asteroseismology: Classification



Kurtz 2010 adapted from Aerts et al. 2010

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Assume that the gas can be treated as a continuum; Thermodynamic properties well defined at each position  $\vec{r}$ 



Let  $\phi$  be a scalar property of the gas.



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Assume that the gas can be treated as a continuum; Thermodynamic properties well defined at each position  $\vec{r}$ 



Let  $\phi$  be a scalar property of the gas.

Two ways to look at time evolution of  $\phi$ :

- 1. At fixed position => <u>Eulerian</u> description
- 2. Following the motion => <u>Lagrangian</u> description

 $\frac{D\phi}{Dt} =$  $\partial \phi$ Dr  $+\nabla\phi$ dt *dt*  $= \frac{\partial \phi}{\partial t} + \vec{\mathbf{v}} \cdot \nabla \phi$ 



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**Continuity equation :** The mass variation within a given volume V must equal, with opposite sign, the mass crossing the surface S that encloses the volume V.



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#### Continuity equation (conservation of mass)





 $\frac{\partial \rho}{\partial t} = -\nabla \cdot \left( \rho \vec{\mathbf{v}} \right)$ 



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#### Following the fluid - Lagrangian description

Continuity equation (conservation of mass)



 $\vec{v}$  - velocity

 $\frac{\mathbf{D}\rho}{\mathbf{D}t} + \rho \,\nabla \cdot \,\vec{\mathbf{v}} = 0$ 



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Following the fluid - Lagrangian description





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Following the fluid - Lagrangian description

- velocity

Continuity equation (conservation of mass)

- density  $\vec{V}$ 

 $\frac{\mathrm{D}\rho}{\mathrm{D}t} + \rho \,\nabla \cdot \,\vec{\mathrm{v}} = 0$ 

Equation of motion: The change in linear momentum of an element of fluid must equal the force acting on it by its surroundings.



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Following the fluid - Lagrangian description

Continuity equation (conservation of mass)

- density  $\vec{\mathbf{v}}$  - velocity

$$\frac{\mathrm{D}\rho}{\mathrm{D}t} + \rho \,\nabla \cdot \,\vec{\mathrm{v}} = 0$$

Equation of motion: The change in linear momentum of an element of fluid must equal the force acting on it by its surroundings.

$$\rho \frac{\mathrm{D}\vec{\mathrm{v}}}{\mathrm{D}t} = -\nabla p + \rho \vec{g} + \vec{F}$$



 $\vec{g} = -\nabla \phi$  - acceleration of gravity  $\vec{F}$ 

-other body forces



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Following the fluid - Lagrangian description

Continuity equation (conservation of mass)



- velocity

Equation of motion (inviscid fluid) (conservation of linear momentum)



 $\vec{g} = -\nabla \phi$  - acceleration of gravity

$$\frac{\mathrm{D}\rho}{\mathrm{D}t} + \rho \,\nabla \cdot \,\vec{\mathrm{v}} = 0$$

$$\rho \frac{\mathrm{D} \vec{\mathrm{v}}}{\mathrm{D} t} = -\nabla p + \rho \vec{g} + \vec{F}$$



-other body forces per unit volume



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-other body forces per unit volume

*p* - pressure

 $\vec{g} = -\nabla \phi$  - acceleration of gravity

+ Poisson equation

$$\nabla^2 \phi = 4\pi G\rho$$

 $\vec{F}$ 



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 $\phi$ 

- Gravitational potential

$$\frac{\mathrm{D}\rho}{\mathrm{D}t} + \rho \,\nabla \cdot \,\vec{\mathrm{v}} = 0$$

$$\rho \frac{\mathrm{D} \vec{\mathrm{v}}}{\mathrm{D} t} = -\nabla p - \rho \nabla \phi$$

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Energy equation (first law of thermodynamics): the change in the internal energy of a system equals the heat supplied to the system minus the work done by the system on its surroundings.



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Energy equation (first law of thermodynamics): the change in the internal energy of a system equals the heat supplied to the system minus the work done by the system on its surroundings.

 $\frac{\mathrm{D}E}{\mathrm{D}t} + p$ 



-heat supplied /mass

*E* -internal energy /mass



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Following the fluid - Lagrangian description

Continuity equation (conservation of mass)



 $\vec{V}$  - velocity

Equation of motion (inviscid fluid) (conservation of linear momentum)



 $\phi$ 

- Gravitational potential

Energy equation (conservation of energy)

q -heat supplied /mass



 $\frac{\mathrm{D}\rho}{\mathrm{D}t} + \rho \,\nabla \cdot \,\vec{\mathrm{v}} = 0$ 

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- pressure  $\phi$  Gravitational potential

**Energy** equation (conservation of energy)

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-heat supplied /mass *F* -internal energy /mass



 $\Gamma_1;\Gamma_3$  - adiabatic exponents

 $\frac{\mathrm{D}\rho}{\mathrm{D}t} + \rho \,\nabla \cdot \,\vec{\mathrm{v}} = 0$ 

 $\rho \frac{\mathbf{D} \vec{\mathbf{v}}}{\mathbf{D} t} = -\nabla p - \rho \nabla \phi$ 

 $\nabla^2 \phi = 4\pi G\rho$ 

 $\frac{\mathrm{D}q}{\mathrm{D}t} = \frac{\mathrm{D}E}{\mathrm{D}t} + p\frac{\mathrm{D}(1/\rho)}{\mathrm{D}t} =$  $=\frac{1}{\rho(\Gamma_3-1)}\left(\frac{\mathrm{D}p}{\mathrm{D}t}-\frac{\Gamma_1p}{\rho}\frac{\mathrm{D}\rho}{\mathrm{D}t}\right)$ 



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Continuity equation (conservation of mass)



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#### Following the fluid - Lagrangian description

Continuity equation (conservation of mass)



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 $\Gamma_1;\Gamma_3$  - adiabatic exponents

#### + Equation of state



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$$\frac{\mathrm{D}\rho}{\mathrm{D}t} + \rho \,\nabla \cdot \,\vec{\mathrm{v}} = 0$$

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### Equilibrium state:

- In static equilibrium
- Spherically symmetric



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#### Equilibrium state:



 $f = f_0 + f'$  - where f' is the Eulerian perturbation  $\delta f$  - is the Lagrangian perturbation

Small perturbations about equilibrium:

In static equilibriumSpherically symmetric

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### Equilibrium state:

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 $f = f_0 + f'$  - where f' is the Eulerian perturbation  $\delta f$  - is the Lagrangian perturbation

Small perturbations about equilibrium:

$$\begin{aligned} \frac{\partial \rho'}{\partial t} + \nabla \cdot (\rho_0 \vec{\mathbf{v}}) &= 0 \\ \rho_0 \frac{\partial \vec{\mathbf{v}}}{\partial t} &= -\nabla p' - \rho_0 \nabla \phi' - \rho' \nabla \phi_0 \\ \nabla^2 \phi' &= 4 \pi G \rho' \\ \frac{\partial \delta q}{\partial t} &= \frac{1}{\rho(\Gamma_{3,0} - 1)} \left( \frac{\partial \delta p}{\partial t} - \frac{\Gamma_{1,0} p_0}{\rho_0} \frac{\partial \delta \rho}{\partial t} \right) \end{aligned}$$



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Adiabatic approximation



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### Equilibrium state:



Small perturbations about equilibrium:  $f = f_0 + f'$  - where f' is the Eulerian perturbation  $\delta f$  - is the Lagrangian perturbation

$$\frac{\partial \rho'}{\partial t} + \nabla \cdot (\rho_0 \vec{v}) = 0$$

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$$\nabla^2 \phi' = 4\pi G \rho'$$

$$\frac{\partial \delta q}{\partial t} = \frac{1}{\rho(\Gamma_{3,0} - 1)} \left( \frac{\partial \delta p}{\partial t} - \frac{\Gamma_{1,0} p_0}{\rho_0} \frac{\partial \delta \rho}{\partial t} \right)$$

Adiabatic approximation

Characteristic time scale for radiation: Sun as a whole: 10<sup>7</sup> years Solar convection zone: 10<sup>3</sup> years



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#### Adiabatic approximation

Characteristic time scale for radiation: Sun as a whole: 10<sup>7</sup> years Solar convection zone: 10<sup>3</sup> years



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Small perturbations about equilibrium:

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$$\rho_0 \frac{\partial \vec{v}}{\partial t} = -\nabla p' - \rho_0 \nabla \phi' - \rho' \nabla \phi_0$$

$$\nabla^2 \phi' = 4\pi G \rho'$$

$$\partial \delta p \qquad \Gamma_{1,0} \rho_0 \ \partial \delta \rho$$

 $\partial t$ 

 $ho_0$ 





 $\partial t$ 

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$$\vec{\mathbf{v}} = \frac{\partial \delta \vec{\mathbf{r}}}{\partial t}$$

$$\delta f = f' + \delta \vec{r} \cdot \nabla f_0$$



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# Summary of perturbed equations

Linear adiabatic pulsation about a static, spherically symmetric equilibrium

$$\rho' + \nabla \cdot (\rho_0 \delta \vec{r}) = 0$$

$$\rho_0 \frac{\partial^2 \delta \vec{r}}{\partial t^2} = -\nabla p' - \rho_0 \nabla \phi' - \rho' \nabla \phi_0$$

$$\nabla^2 \phi' = 4\pi G \rho'$$

$$p' + \delta \vec{r} \cdot \nabla p_0 = \frac{\Gamma_{1,0} p_0}{\rho_0} (\rho' + \delta \vec{r} \cdot \nabla \rho_0)$$



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$$p' + \delta \vec{r} \cdot \nabla p_0 = \frac{\Gamma_{1,0} p_0}{\rho_0} (\rho' + \delta \vec{r} \cdot \nabla \rho_0)$$

Variables: 4 ( $\varrho$ ', p',  $\phi$ ',  $\delta$ r)

**Equations:** 4

Thus: system of equation is closed, so far as equilibrium quantities are known.

=> can solve it to get solutions for the 4 variables.



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Consider the spherical coordinates  $(r, \theta, \varphi)$ 

Variables  $(\varrho', p', \phi', \delta \vec{r})$  are function of:  $r, \theta, \phi, t$ 





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Variables  $(\varrho', p', \phi', \delta \vec{r})$  are function of:  $r, \theta, \phi, t$ 

The equations admit solutions of the type:

 $p'(\mathbf{r},\theta,\varphi,t) = \operatorname{Re}[p'(r)Y_l^m(\theta,\varphi)e^{-i\omega t}]$   $\rho'(\mathbf{r},\theta,\varphi,t) = \operatorname{Re}[\rho'(r)Y_l^m(\theta,\varphi)e^{-i\omega t}]$   $\phi'(\mathbf{r},\theta,\varphi,t) = \operatorname{Re}[\phi'(r)Y_l^m(\theta,\varphi)e^{-i\omega t}]$   $\delta \vec{\mathbf{r}}(\mathbf{r},\theta,\varphi,t) = \operatorname{Re}\left\{\left[\xi_r(r)Y_l^m\hat{\mathbf{a}}_r + \xi_h(r)\left(\frac{\partial Y_l^m}{\partial \theta}\hat{\mathbf{a}}_\theta + \frac{1}{\sin\theta}\frac{\partial Y_l^m}{\partial \phi}\hat{\mathbf{a}}_\phi\right)\right]e^{-i\omega t}\right\}$ 



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Consider the spherical coordinates  $(r, \theta, \varphi)$ 

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The equations admit solutions of the type:

$$p'(\mathbf{r},\theta,\varphi,t) = \operatorname{Re}[p'(r)Y_l^m(\theta,\varphi)e^{-i\omega t}]$$

$$\rho'(\mathbf{r},\theta,\varphi,t) = \operatorname{Re}[\rho'(r)Y_l^m(\theta,\varphi)e^{-i\omega t}]$$

$$\phi'(\mathbf{r},\theta,\varphi,t) = \operatorname{Re}[\phi'(r)Y_l^m(\theta,\varphi)e^{-i\omega t}]$$

$$\delta\vec{\mathbf{r}}(\mathbf{r},\theta,\varphi,t) = \operatorname{Re}\left\{\left[\xi_r(r)Y_l^m\hat{\mathbf{a}}_r + \xi_h(r)\left(\frac{\partial Y_l^m}{\partial \theta}\hat{\mathbf{a}}_\theta + \frac{1}{\sin\theta}\frac{\partial Y_l^m}{\partial \phi}\hat{\mathbf{a}}_\phi\right)\right]e^{-i\omega t}\right\}$$



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l – angular degree: the number of nodes on the sphere



*m* - azimuthal order: *|m|* =number of nodes along the equator => orientation on the sphere

Note:  $|m| \leq l$ 



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l - angular degree: the number of nodes on the sphere



m - azimuthal order: |m| =number of nodes along the equatorNote:  $|m| \le l$  $\implies$  orientation on the sphere



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adapted from Aerts et al. 2010





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Consider the spherical coordinates  $(r, \theta, \varphi)$ 

Variables  $(\underline{\rho}', \underline{\rho}', \phi', \delta \vec{r})$  are function of:  $r, \theta, \phi, t$ 

The equations admit solutions of the type:

$$p'(\mathbf{r},\theta,\varphi,t) = \operatorname{Re}[p'(r)Y_l^m(\theta,\varphi)e^{-i\omega t}]$$
  

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$$\delta\vec{\mathbf{r}}(\mathbf{r},\theta,\varphi,t) = \operatorname{Re}\left\{\left[\xi_r(r)Y_l^m\hat{\mathbf{a}}_r + \xi_h(r)\left(\frac{\partial Y_l^m}{\partial \theta}\hat{\mathbf{a}}_\theta + \frac{1}{\sin\theta}\frac{\partial Y_l^m}{\partial \phi}\hat{\mathbf{a}}_\phi\right)\right]e^{-i\omega t}\right\}$$



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Substituting the solutions on the perturbed equations ... and after significant algebra

$$\frac{d\xi_r}{dr} = -\left(\frac{1}{\Gamma_{1,0}p_0}\frac{dp_0}{dr} + \frac{2}{r}\right)\xi_r + \left(\frac{S_l^2}{\omega^2} - 1\right)\frac{1}{c_0^2\rho_0}p' + \frac{l(l+1)}{r^2\omega^2}\phi'$$
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4 variables:  $\xi_r$ , p',  $\varphi'$ ,  $d\varphi'/dr$ 4<sup>th</sup> order system

Note1: all derivatives are total derivatives because the functions depend on r only



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Note2: equations depend on l but not on m, thus the eigenvalues  $\omega$  cannot depend on m.



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4 variables:  $\xi_r$ , p',  $\phi$ ',  $d\phi$ '/dr 4<sup>th</sup> order system

This system, together with the boundary conditions, forms an eigenvalue problem => Solving it provide the eigenvalues,  $\omega$ , and eigenfunctions,  $\xi_r$ , p',  $\varphi'$ ,  $d\varphi'/dr$ .



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 $S_l$ : Lamb frequency



 $N_0$ : Buoyancy frequency  $N_0^2 = g_0 \left[ \frac{1}{\Gamma_{10}} \frac{d \ln p_0}{dr} - \frac{d \ln \rho_0}{dr} \right]$ 



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$$S_{l}: \text{ Lamb frequency} \qquad S_{l}^{2} = \frac{l(l+1)}{r^{2}}c_{0}^{2} \qquad N_{0}^{2} > 0 \Rightarrow Q_{2}^{*} > Q_{2}$$

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Fourth order system => 4 boundary conditions required

- $\geq$  2 conditions at *r*=0
- > 2 condition at *r*=R



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- $\geq$  2 conditions at *r*=0
- $\triangleright$  2 condition at *r*=R

#### Conditions at *r*=0

Obtained by imposing regularity of the solutions at the centre

Expand the equations near  $r=0 \implies$  find that

 $p' \sim O(r^l)$ ;  $\phi' \sim O(r^l)$ ;  $\xi_r \sim O(r^{\alpha})$  with  $\alpha = 1$  for l = 0 $\alpha = l - 1$  for l > 0



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Consequently:

 $\frac{d\phi'}{dr} = \frac{l}{r}\phi' \quad ; \quad \frac{dp'}{dr} = \frac{l}{r}p' \quad ; \quad \frac{d\xi_r}{dr} = \frac{\alpha}{r}\xi_r$ 



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1<sup>st</sup> condition: matching  $\phi$ ' and its derivative to solution for vacuum field

 $\boldsymbol{\phi}' \sim \mathcal{O}(r^{-l-1})$ 



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2<sup>nd</sup> condition: depends on how the atmosphere is treated

e.g. assuming free surface  $\Rightarrow \delta p'=0$ (But this is not adequate for a real star!)

$$p' + \xi_r \frac{dp_0}{dr} = 0$$

A better option is to make the numerical solutions match onto the analytical solutions for an isothermal atmosphere.



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#### Eigenvalue problem

We reduced the problem to 1D

Equations + boundary conditions

=> admit non-trivial solutions only for a discrete values of frequencies

This set of frequencies is numbered by an integer *n*, *the radial order* 





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#### Eigenvalue problem

In summary: eigenfrequencies are discrete and characterized by three quantum numbers:

ω=ω(n,l,m)

*n —radial order: |n| related to the number of nodes along the radial direction* 

l – angular degree: the number of nodes on the sphere

*m* - azimuthal order: *|m|* =number of nodes along the equator => orientation on the sphere



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#### Eigenvalue problem

In summary: eigenfrequencies are discrete and characterized by three quantum numbers:

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#### Equations for the depth dependent amplitudes

$$\begin{aligned} \frac{d\xi_r}{dr} &= -\left(\frac{1}{\Gamma_{1,0}p_0}\frac{dp_0}{dr} + \frac{2}{r}\right)\xi_r + \left(\frac{S_l^2}{\omega^2} - 1\right)\frac{1}{c_0^2\rho_0}p' + \frac{l(l+1)}{r^2\omega^2}\phi' \\ \frac{dp'}{dr} &= \rho_0(\omega^2 - N_0^2)\xi_r - \rho_0\frac{d\phi'}{dr} + \frac{1}{\Gamma_{1,0}p_0}\frac{dp_0}{dr}p' \\ \frac{1}{r^2}\frac{d}{dr}\left(r^2\frac{d\phi'}{dr}\right) &= 4\pi G\left(\frac{p'}{c_0^2} + \frac{\rho_0N_0^2}{g_0}\xi_r\right) + \frac{l(l+1)}{r^2}\phi' \end{aligned}$$

Equations depend on l, but not on m

 $\Rightarrow$  In a spherically symmetric star, the eigenvalues are independent of m



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 $\implies$  In a spherically symmetric star, the eigenvalues are independent of m



Note: That is not the case if the star rotates or has a magnetic field, braking the symmetry.



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#### Waves in a spherically symmetric star







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The full solutions must be obtained numerically. However, under particular approximations, approximate analytical solutions can be derived.



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#### The Cowling approximation

Neglect the perturbation to the gravitational potential,  $\phi'$ => reduces the system to 2<sup>nd</sup> order

Valid when l is large or |n| is large

 $\vec{g}' = \nabla \Phi'$  $\Phi' = G \int \frac{\rho'(\vec{r}', t)}{|\vec{r} - \vec{r}'|} dV$ 



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2 variables:  $\xi_r$ , p' 2<sup>nd</sup> order system



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Following Deubner and Gough 1984

Work under Cowling approximation

Assume that locally oscillations can be treated as in a plane-parallel layer under constant gravity (i.e., neglect derivatives of g and r)

(See also, Gough 93)



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Assume that locally oscillations can be treated as in a plane-parallel layer under constant gravity (i.e., neglect derivatives of g and r)

Define the new variable:

$$X = c_0^2 \rho_0^{1/2} \nabla \cdot \delta \vec{r}$$



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In terms of the new variable the  $2^{nd}$  order system of equations can be reduced to a single  $2^{nd}$  order wave equation:

$$\frac{d^2X}{dr^2} + k_r^2 X = 0$$

Where  $k_r$  is the local radial wavenember



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Recall the solutions of the wave equation with constant k





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General solution is:



where *A* and *B* are complex constants



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Recall the solutions of the wave equation with constant k



General solution is:

$$y = Ae^{ikx} + Be^{-ikx}$$

where A and B are complex constants

 $k^{2} > 0 \implies k \text{ is real }; \text{ Re}\{y\} = a \cos kx + b \sin kx$  $=> oscillatory \ behaviour$ 

>  $k^2 < 0 \implies k = i |k|$ ; Re{y}=  $ae^{-lk|x} + be^{lk|x}$ 

=> exponential grow or decay



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In the star  $k_r$  is not constant!

$$\frac{d^2X}{dr^2} + k_r^2 X = 0$$



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$$k_r^2 = \frac{1}{c_0^2} \left[ S_l^2 \left( \frac{N_0^2}{\omega^2} - 1 \right) + \omega^2 - \omega_c^2 \right]$$
$$\omega_c^2 = \frac{c_0^2}{4H^2} \left( 1 - 2\frac{dH}{dr} \right)$$
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What are the regions where:  $k_r^2 > 0$  (oscillatory behaviour) ?  $k_r^2 < 0$  (exponentially decaying) ?



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Find the turning points of the equation, where  $k_r^2 = 0$ 

$$\omega_{l\pm}^{2} = \frac{1}{2} \left( S_{l}^{2} + \omega_{c}^{2} \right) \pm \frac{1}{2} \sqrt{\left( S_{l}^{2} + \omega_{c}^{2} \right)^{2} - 4 S_{l}^{2} N_{0}^{2}}$$



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Thus, we can rewrite:

$$k_{r}^{2} = \frac{1}{c_{0}^{2}} \left[ \omega^{2} - \omega_{l+}^{2} \right] \left[ \omega^{2} - \omega_{l-}^{2} \right]$$



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► Modes propagate where  $k_r^2 > 0$  =>  $\omega > \omega_{l+}$  or  $\omega < \omega_{l-}$ 

> Modes are evanescent where  $k_r^2 < 0 \implies$ 

$$\omega_{l-} < \omega < \omega_{l+}$$

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## A closer look at the solutions

A closer look at the two families of solutions

 $\triangleright$  High frequency modes  $\omega^2 >> N_0^2$ 







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Except near the surface









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#### $\blacktriangleright$ High frequency modes $\omega^2 >> N_0^2$

Except near the surface



Dispersion relation for acoustic wave!







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#### $\blacktriangleright$ High frequency modes $\omega^2 >> N_0^2$

Except near the surface



Dispersion relation for acoustic wave!

ω increases as k increases
=> the radial order n increases with the frequency



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 $k_r^2 = \frac{1}{c^2} \left| S_l^2 \left( \frac{N_0^2}{\omega^2} - 1 \right) \right|$ 

10000

5000

1000

500

100 50

0.0

0.2

ν (μHz)

 $+\omega^2 - \omega_c^2$ 

500

Adapted from Aerts et al. 201

100

50

0.6

 $\tau/R$ 

0.4

0.8

1.0

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Except near the surface



#### Lower turning point







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Except near the surface

$$k_r^2 \approx \frac{\omega^2 - S_l^2}{c_0^2} = \frac{\omega^2}{c_0^2} - \frac{l(l+1)}{r^2}$$

#### Lower turning point $\omega^2 = S_l^2$









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#### Lower turning point $\omega^2 = S_l^2$



 $r_{l,l}$  increases as l increases

=> larger degree modes have shallower cavities

For fixed *l*:  $r_{1,l}$  increases as  $\omega$  increases

=> higher frequency modes propagate deeper, for fixed degree

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- $r_{l,l}$  increases as l increases
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Near the surface



#### Upper turning point







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 $k_r^2 \approx \frac{\omega^2 - \omega_c^2}{2}$ 

 $C_0$ 

$$k_r^2 = \frac{1}{c_0^2} \left[ S_l^2 \left( \frac{N_0^2}{\omega^2} - 1 \right) + \omega^2 - \omega_c^2 \right]$$

 $\triangleright$  High frequency modes  $\omega^2 >> N_0^2$ 

Near the surface

Upper turning point  $\omega^2 = \omega_c^2$ 





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#### A closer look at the two families of solutions



 $\triangleright$  High frequency modes  $\omega^2 >> N_0^2$ 

Near the surface

Upper turning point  $\omega^2 = \omega_c^2$ 

$$\omega \approx \frac{c_0}{2H} \left[ 1 - 2\frac{dH}{dr} \right]$$

 $k_r^2 \approx \frac{\omega^2 - \omega_c^2}{c}$ 





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Trapping of modes occurs up to  $\sim 5.3$  mHz in the sun ... but partial reflection occurs at even higher frequencies



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Trapping of modes occurs up to  $\sim 5.3$  mHz in the sun ... but partial reflection occurs at even higher frequencies

Modes with frequencies lower than  $\sim 2$  mHz in the sun are reflected below the photosphere

=> not so affected by the details of the outermost layers

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$$k_r^2 \approx \frac{S_l^2}{c_0^2} \left[ \frac{N_0^2}{\omega^2} - 1 + \frac{\omega^2}{S_l^2} - \frac{\omega_c^2}{S_l^2} \right] \approx \frac{l(l+1)}{r^2} \left[ N_0^2 - \omega^2 \right] \frac{1}{\omega^2}$$

$$k_h^2$$







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Dispersion relation for gravity wave.







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$$k_{r}^{2} \approx \frac{S_{l}^{2}}{c_{0}^{2}} \left[ \frac{N_{0}^{2}}{\omega^{2}} - 1 + \frac{\omega^{2}}{S_{l}^{2}} - \frac{\omega_{c}^{2}}{S_{l}^{2}} \right] \approx \frac{l(l+1)}{r^{2}} \left[ N_{0}^{2} - \omega^{2} \right] \frac{1}{\omega}$$

$$k_{h}^{2}$$

$$\omega^{2} \approx \frac{N_{0}^{2}}{1 + \frac{k_{r}^{2}}{k_{h}^{2}}}$$

Dispersion relation for gravity wave.

 $\omega < N_0$ 

 $\omega$  decreases as  $k_r$  increases => |n| increases as frequency decreases

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 $\blacktriangleright$  Low frequency modes  $\omega^2 \ll S_l^2$ 



 $k_r^2 = \frac{1}{c_0^2} \left[ S_l^2 \left( \frac{N_0^2}{\omega^2} - 1 \right) + \omega^2 - \omega_c^2 \right]$ 



Dispersion relation for gravity wave.

Smaller  $k_r/k_h \implies$  Larger  $\lambda_r/\lambda_h \implies$  larger  $\omega$  $\implies$  larger frequencies for "needle-like" motion

The frequency of a gravity wave is always smaller that  $N_0$ 

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$$k_{r}^{2} \approx \frac{S_{l}^{2}}{c_{0}^{2}} \left[ \frac{N_{0}^{2}}{\omega^{2}} - 1 + \frac{\omega^{2}}{S_{l}^{2}} - \frac{\omega_{c}^{2}}{S_{l}^{2}} \right] \approx \frac{l(l+1)}{r^{2}} \left[ N_{0}^{2} - \omega^{2} \right] \frac{1}{\omega^{2}}$$
  
Turning points







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$$k_{r}^{2} \approx \frac{S_{l}^{2}}{c_{0}^{2}} \left[ \frac{N_{0}^{2}}{\omega^{2}} - 1 + \frac{\omega^{2}}{S_{l}^{2}} - \frac{\omega_{c}^{2}}{S_{l}^{2}} \right] \approx \frac{l(l+1)}{r^{2}} \left[ N_{0}^{2} - \omega^{2} \right] \frac{1}{\omega^{2}}$$
  
Turning points  $\omega^{2} = N_{0}^{2}$ 





Gravity waves propagate only in convectively stable regions!



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 $\triangleright$  Low frequency modes  $\omega^2 \ll S_l^2$ 



 $k_r^2 \approx \frac{S_l^2}{c_0^2} \left[ \frac{N_0^2}{\omega^2} - 1 + \frac{\omega^2}{S_l^2} - \frac{\omega_c^2}{S_l^2} \right] \approx \frac{l(l+1)}{r^2} \left[ N_0^2 - \omega^2 \right] \frac{1}{\omega^2}$  $k_{\rm h}^2$ Turning points  $\omega^2 = N_0^2$ 





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# The case of an evolved star

The case of an evolved star

Propagation diagram for the sun and a subgiant star





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The case of an evolved star

Propagation diagram for the sun and a subgiant star





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# Acoustic and internal gravity waves

# Acoustic and gravity waves

#### Acoustic wave









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# Acoustic and gravity waves

#### Internal gravity wave

http://www.phys.ocean.dal.ca/programs/doubdiff/pics/iw1.mpeg





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# Acoustic and gravity waves Summary

#### Acoustic waves

- Maintained by gradient of pressure fluctuation;
- Radial or non-radial;
- Propagate in convectively stable or non-stable regions

#### Internal gravity waves

- Maintained by gravity acting on density fluctuation;
- Always non-radial;
- Propagate in convectively stable regions only



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# Numerical solutions

#### Eigenfrequencies





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#### Eigenfrequencies

Aerts et al. 2010





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#### Eigenfrequencies

Acoustic modes: n > 0

Gravity modes: n < 0



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#### Eigenfrequencies





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#### Eigenfunctions

Aerts et al. 2010





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### Numerical results

#### Eigenfunctions

Cunha et al. 2015





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A number of important things that were left out > The actual asymptotic analysis:

=> analytical solutions for the eigenfunctions and eigenfrequencies

Frequency combinations (large separation, small separations, ratios, etc)

Inference methodologies (forward modelling, inverse modelling, glitches, etc)

> Deviations from spherical symmetry (rotation, magnetic effects, application of the variational principle)

Mode excitation (stochastic, coherent)





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Linear, adiabatic oscillations in the Cowling approximation.

High *n*, low *l*, acoustic oscillations:

$$v_{nl} \approx \left(n + \frac{l}{2} + \alpha\right) \Delta v_0 + higher order terms$$
  
where  $\Delta v_0 = \left(2\int_0^R \frac{dr}{c}\right)^{-1}$ 

- $\Delta v_0$  prop  $(M/R^3)^{1/2}$
- $\alpha$  function of v and is due to surface effects
- Note:  $v=\omega/2\pi$

Adiabatic oscillations in the Cowling approximation.

High *n*, low *l*, acoustic oscillations:



$$v_{nl} \approx \left(n + \frac{l}{2} + \alpha\right) \Delta v_0 + \dots$$

 $\Delta v_0 \text{ prop } (M/R^3)^{1/2}$ 

Large separations  $\Delta v_{nl}$ 

$$v_{nl} \approx \left(n + \frac{l}{2} + \alpha\right) \Delta v_0 + higher order terms$$

Large separations  $\Delta v_{nl}$ 

$$v_{nl} \approx \left(n + \frac{l}{2} + \alpha\right) \Delta v_0 + higher order terms$$

$$\Delta v_{nl} = v_{n+1,l} - v_{n,l} \approx \Delta v_0 \qquad \alpha \, (M/R^3)^{1/2}$$



Adiabatic oscillations in the Cowling approximation.

High *n*, low *l*, acoustic oscillations:

$$v_{nl} \approx \left(n + \frac{l}{2} + \alpha\right) \Delta v_0 - \left[Al(l+1) - \delta\right] \frac{\Delta v_0}{v_{nl}} + \dots$$
  
where  $A = \frac{1}{4\pi^2 \Delta v_0} \left[\frac{c(R)}{R} - \int_0^R \frac{dc}{r}\right]$ 

small separations  $\delta v_{nl}$ 

$$v_{nl} \approx \left(n + \frac{l}{2} + \alpha\right) \Delta v_0 - \left[Al(l+1) - \delta\right] \frac{\Delta v_0}{v_{nl}} + \dots$$
where  $A = \frac{1}{4\pi^2 \Delta v_0} \left[\frac{c(R)}{R} - \int_0^R \frac{dc}{r}\right]$ 

$$\delta v_{nl} = v_{n,l} - v_{n-1,l+2} \approx -(4l+6) \frac{\Delta v_0}{4\pi^2 v_{n,l}} \int_0^R \frac{dc}{r}$$
Schematic  $\delta v_{nl}$   $\delta v_{nl}$ 

n-1,

Sun as a star



Enjoy the rest of the school and have a great stay at Azores!

THE END